

Intel® Edison Breakout Board

Hardware Guide

October 2014

Revision 004

Document Number: 331190-004



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Revision History

Revision	Description	Date
ww32	Initial release.	August 4, 2014
ww34	Minor edits.	August 20, 2014
001	First public release.	September 9, 2014
002	Minor corrections.	September 15, 2014
003	Added handling information.	September 30, 2014
004	Added details on the breakout board jumpers and USB connectivity.	October 16, 2014





1 Introduction

This document describes the Intel® Edison breakout board.

The Intel® Edison breakout board is designed to expose the native 1.8 V I/O of the Intel® Edison module. The board consists of power supply, battery recharger, USB OTG power switch, UART to USB bridge, USB OTG port, and I/O header.

1.1 References

Table 1 Product-specific documents

Reference	Name	Number/location
331188	Intel® Edison Board Support Package User Guide	
331189	Intel® Edison Module Hardware Guide	
331190	Intel® Edison Breakout Board Hardware Guide	(This document)
331191	Intel® Edison Kit for Arduino* Hardware Guide	
331192	Intel® Edison Native Application Guide	
331193	Intel® Edison Quick Start Guide	
[RN]	Intel® Edison Board Support Package Release Notes	
[GSG]	Intel® Edison Getting Started Guide	https://communities.intel.com/docs/DOC-23147
H49905	Intel® Edison Breakout Board Schematic	https://communities.intel.com/docs/DOC-23323

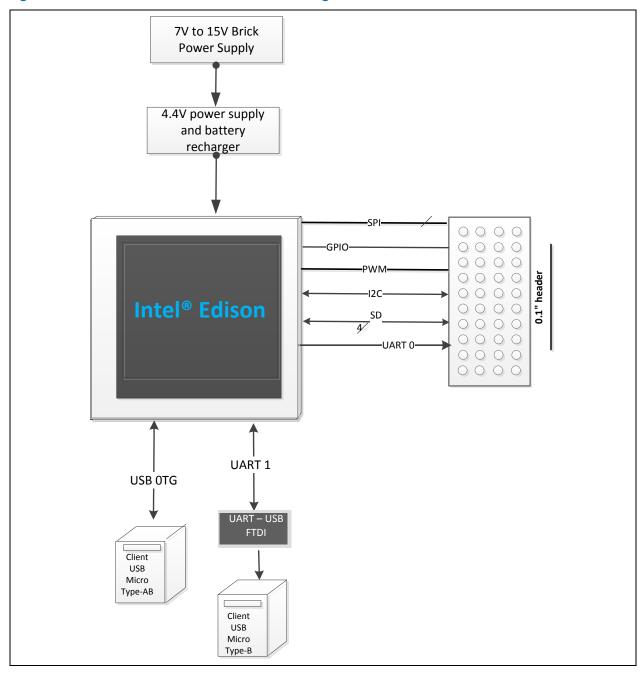




2 High-Level Functional Description

Figure 1 provides the block diagram for the Intel® Edison breakout board.

Figure 1 Intel® Edison breakout board block diagram





2.1 Intel® Edison breakout board jumpers

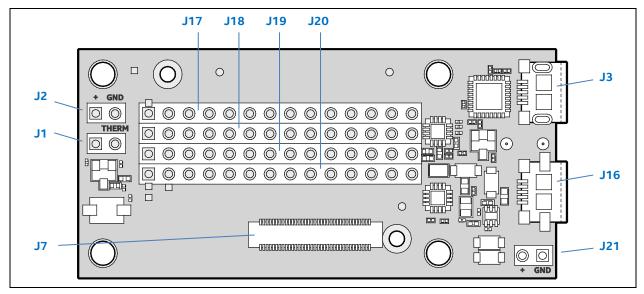
This section explains some of the jumpers on the Intel® Edison breakout board. See Figure 2 for jumper locations.

- The left pin (the square one) on J2 is +V battery; the right pin is ground.
- J2 is the battery connector. If you want to power the breakout board with a rechargeable lithium-ion battery, attach it to J2. (Refer to Figure 2 for battery polarity.) When you attach a rechargeable lithium-ion battery, the breakout board will recharge the battery whenever power is applied via J21 or J22, or via J3 (when the board is attached to a USB host).

Note: If you decide to use a battery pack on J2, we recommend a battery with a built-in thermistor. This thermistor should attach to the charger on the breakout board. If you opt for the built-in thermistor, remove the jumper on J1 and connect the thermistor to the pin labeled THERM in Figure 2. If you choose not to use a battery with built-in thermistor, leave the jumper in place.)

- J3 is a micro USB FTDI serial-to-USB converter. The Linux console will output serial stream to this USB connector.
- J16 is a fully USB compatible, micro AB, OTG (power "on the go") port. If you plug a micro A cable into this port, the Intel® Edison module will connect to a PC as the host; if you plug a micro B cable into this port, the Intel® Edison module will connect to the PC as a device. (See the USB A female to micro A male cable, Digikey P/N 10-00649 839-1105-ND in Figure 7.)
- For jumpers J17 through J20, the first pin on the left (the square one) is pin 1.
- J21 is the main power input. Apply 7 to 15 VDC with the polarity shown.
- J22 (on the bottom side of the board; see Figure 3) is for a power jack (not installed). You can purchase a 2.5 mm barrel jack (see the mini-breakout power jack in Figure 7, Digikey P/N PJ-002BH-SMT-TR CP-002BHPJCT-ND) and solder it to the bottom side of the board as shown in Figure 3. The input voltage to J22 is also 7 to 15 VDC.

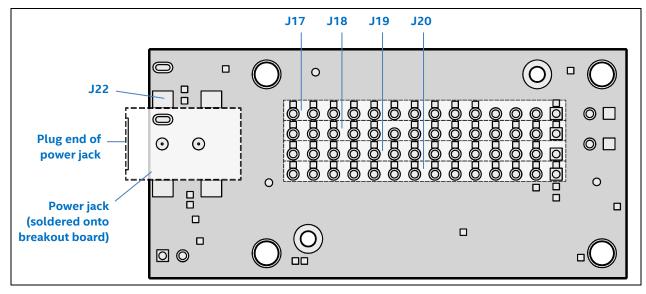
Figure 2 Breakout board jumpers (top of board)



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Figure 3 Breakout board jumpers (bottom of board)



2.1.1 USB interface

The Intel® Edison breakout board has a single USB 2.0 interface. This interface is the primary method for downloading code on J16. It is designed to support full USB "On the Go" (OTG) connections, using the ID signal. If you plug in a USB micro B connector, the breakout board will act as a USB device, and it will take its power from the USB connector.

If you plug a USB micro A connector into it, the breakout board will function as a host. When you use the Intel® Edison breakout board as a host in this manner, you must supply external power via J21 or J22. The breakout board will convert that voltage to supply 5 V to the USB connector.

Note: If you power the breakout board with a battery, it will not supply power as a USB host.



2.2 Intel® Edison breakout board expansion header

This section explains the expansion header.

When the pin mode is chosen as GPIO, it can be programmed as an output or input. When programmed as an input, a GPIO can serve as an interrupt or wake source. Inputs have programmable pullups or pulldowns. Pullup value can be 2, 20, or 50 kohm. I2C pins also have an additional 910 ohm value.

When in general purpose mode, input GPIO signals enter a glitch filter by default, before reaching the edge detection registers. To ensure that a pulse is detected by the edge detection register, the pulse should be five clock cycles long.

- 100 ns for a 50 MHz clock when SoC is in S0 state.
- 260 ns for 19.2 MHz clock when SoC is in S0i1 or S0i2 State.
- 155.5 µs for 32 kHz clock (RTC) when SoC is in S0i3 State.

Most GPIO capable pins are configured as GPIO inputs during the assertion of all resets and they remain inputs until configured otherwise.

As outputs, the GPIOs can be individually cleared or set. They can be pre-programmed to either state when entering standby. Output drive is ± 3 mA.

Table 2 Intel® Edison breakout board expansion header signal list

Pin			Description
J17 - pin 1	GP182_PWM2		GPIO capable of PWM output.
J17 - pin 2	NC		No connect.
J17 - pin 3	NC		No connect.
J17 - pin 4	VIN		7 to 15 V.
J17 - pin 5	GP135	UART2_TX	GPIO, UART2 transmit output.
J17 - pin 6	RCVR_MODE		Firmware recovery mode.
J17 - pin 7	GP27	I2C6_SCL	GPIO,IC26 SCL output open collector.
J17 - pin 8	GP20	I2C1_SDA	GPIO, I2C1 data open collector.
J17 - pin 9	GP28	I2C6_SDA	GPIO, I2C6 data open collector.
J17 - pin 10	GP111	SSP5_FS1	GPIO, SSP2 chip select 2 output.
J17 - pin 11	GP109	SSP5_CLK	GPIO, SSP5 clock output.
J17 - pin 12	GP115	SSP5_TXD	GPIO, SSP5 transmit data output.
J17 - pin 13	OSC_CLK_OUT_0		High speed clock output.
J17 - pin 14	GP128	UART1_CTS	GPIO, UART1 clear to send input.
J18 - pin 1	GP13_PWM1		GPIO capable of PWM output.
J18 - pin 2	GP165		GPIO
J18 - pin 3	GPI_PWRBTN_N		Power button input.
J18 - pin 4	MSIC_SLP_CLK2		32 kHz sleep clock.
J18 - pin 5	V_VBAT_BKUP		RTC backup battery input.
J18 - pin 6	GP19	I2C1_SCL	GPIO,IC21 SCL output open collector.
J18 - pin 7	GP12_PWM0		GPIO capable of PWM output.



18 - pin 8	Pin			Description
J18 - pin 9		GP183 D\\/M3		•
J18 - pin 10		_		
J18 - pin 11 GP114 SSP5_RX GPI0, SSP5 receive data input. J18 - pin 12 GP129 UART1_RTS GPI0, UART1 ready to send output. J18 - pin 13 GP130 UART1_RX GPI0, UART1 receive data input. J18 - pin 14 FW_RCVR Firmware recovery, active high on boot. J20 - pin 1 V_VSYS System input power. J20 - pin 2 V_V3P30 System 3.3 V output. J20 - pin 3 GP134 UART2_RX UART2_RX (input). J20 - pin 4 GP45 COMPASS_DRDY GPI0, compass data ready input. J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input 2. J20 - pin 7 GP15 GP47 ACCELEROMETER_INT_2 GPI0, gyro interrupt input 2. J20 - pin 8 GP84 SD_CLK_FB GPI0, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 RX data input. J20 - pin 10 GP41 SSP2_FS GPI0, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD command. J20 - pin 13 GP80 SD_DAT0 GPI0, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 2 V_V1P80 System 1.8 V I/O output power. J19 - pin 3 GND GP0, SD commeter interrupt input. J19 - pin 6 GP48 ACCELEROMETER_INT_1 GPI0, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPI0, SD cacelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPI0, gyro data ready input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPI0, accelerometer interrupt input. J19 - pin 9 GP14 AUDIO_CODEC_INT GPI0, SDP2 clock output. J19 - pin 10 GP40 SSP2_CLK GPI0, SSP2 transmit data output. J19 - pin 10 GP40 SSP2_CLK GPI0, SSP2 transmit data output. J19 - pin 10 GP40 SSP2_CLK GPI0, SSP2 transmit data output. J19 - pin 10 GP40 SSP2_CLK GPI0, SSP2 transmit data output. J19 - pin 10 GP40 SSP2_CLK GPI0, SSP2 transmit data output. J19 - pin 11 GP43 SSP2_CLK GPI0, SSP2 transmit data output.	-	-	SSD5 ESO	
J18 - pin 12				
J18 - pin 13	-			'
J18 - pin 14				•
J20 - pin 1			UARTI_RX	·
J20 - pin 2	-			
J20 - pin 3		_		· · · ·
J20 - pin 4 GP45 COMPASS_DRDY GPIO, compass data ready input.	-	_		
J20 - pin 5				
J20 - pin 6			_	, ,
J20 - pin 7 GP15 GP16. J20 - pin 8 GP84 SD_CLK_FB GPI0, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPI0, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD command. J20 - pin 13 GP80 SD_DATO GPI0, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 2 V_V1P80 System 1.8 V I/O output power. J19 - pin 3 GND Ground. J19 - pin 4 GP44 ALS_INT_N GPI0, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPI0, accelerometer interrupt input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPI0, uadio codec interrupt input. J19 - pin 9 GP40 SSP2_CLK GPI0, SSP2 clock output. J19 - pin 11 GP43 SSP2_TXD GPI0, SCP2 transmit data output. J19 - pin 12 GP77 SD_CDN GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPI0, SD card detect low input. J19 - pin 14 GP10, SD card detect low input. J19 - pin 15 GP10, SD card detect low input. J19 - pin 15 GP10, SD card detect low input. J10 - MT - MT - MT - MT - MT - MT -			ACCELEROMETER_INT_2	GPIO, accelerometer interrupt input 2.
J20 - pin 8 GP84 SD_CLK_FB GPIO, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPIO, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPIO, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPIO, SD clock output. J20 - pin 12 GP79 SD_CMD GPIO, SD command. J20 - pin 13 GP80 SD_DATO GPIO, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 2 V_V1P80 System 1.8 V I/O output power. J19 - pin 3 GND Ground. J19 - pin 4 GP44 ALS_INT_N GPIO, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPIO, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPIO, gyro data ready input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPIO, udio codec interrupt input. J19 - pin 10 GP40 SSP2_CLK GPIO, SSP2 clock output. J19 - pin 11 GP43 SSP2_TXD GPIO, SD card detect low input. J19 - pin 12 GP77 SD_CDN GPIO, SD data 2	J20 - pin 6	GP49	GYRO_INT	, ,
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J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPIO, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPIO, gyro data ready input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPIO, UART 1 Tx output. J19 - pin 9 GP14 AUDIO_CODEC_INT GPIO, audio codec interrupt input. J19 - pin 10 GP40 SSP2_CLK GPIO, SSP2 clock output. J19 - pin 11 GP43 SSP2_TXD GPIO, SSP2 transmit data output. J19 - pin 12 GP77 SD_CDN GPIO, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPIO, SD data 2	J19 - pin 3	GND		Ground.
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J19 - pin 9 GP14 AUDIO_CODEC_INT GPIO, audio codec interrupt input. J19 - pin 10 GP40 SSP2_CLK GPIO, SSP2 clock output. J19 - pin 11 GP43 SSP2_TXD GPIO, SSP2 transmit data output. J19 - pin 12 GP77 SD_CDN GPIO, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPIO, SD data 2	J19 - pin 7	RESET_OUT#		System reset out low.
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J19 - pin 12 GP77 SD_CDN GPIO, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPIO, SD data 2	J19 - pin 10	GP40	SSP2_CLK	GPIO, SSP2 clock output.
J19 - pin 13	J19 - pin 11	GP43	SSP2_TXD	GPIO, SSP2 transmit data output.
	J19 - pin 12	GP77	SD_CDN	GPIO, SD card detect low input.
J19 - pin 14	J19 - pin 13	GP82	SD_DAT2	GPIO, SD data 2
	J19 - pin 14	GP83	SD_DAT3	GPIO, SD data 3



2.3 Intel® Edison breakout board expansion power supply

Intel® Edison is a low-power device. In general, it does not draw more than 200 mA with 600 mA short duration spikes during Wi-Fi transmit. Therefore, an Intel® Edison device may run on USB power (when configured as a device), or an external power adapter from 7 to 15 V.

Power from the external power adapter goes to a DC-DC converter and down-converted to 5 V. The 5 V rail is diode ORed with the USB VBUS rail. This power goes to a battery recharger IC, which limits the output voltage to 4.4 V. This voltage is in the safe range for the Edison module VSYS. The VSYS power range is 3.15 to 4.5 V. This allows VSYS to run off a standard lithium-ion battery. The charger IC is configured to limit the input power to 1. The charger is programmed to charge at 190 mA. This charger is designed to charge standard lithium-ion batteries with 4.2 V maximum charging voltage. You are responsible for choosing a suitable battery and following all safety precautions, to prevent overcharging or charging when the battery temperature is too high.

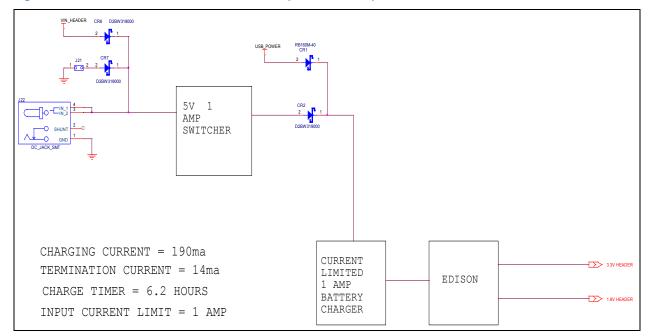
The drawback to this design is that the linear supply power drop places a limit on the total power through the Intel® Edison board and the 3.3 and 1.8 V supplies. The power loss through the charger will be (4.4 to 5 V) • current. In this case, you should attempt to limit average current through the Intel® Edison board and its power rails to approximately 0.75 A.

The recharger IC on the Intel® Edison breakout board has input current limit and overtemperature shutdown. Assure the end design does not trip these protection mechanisms.

Some considerations of the power distribution in the Intel® Edison breakout board:

- 1. USB host mode always requires use of an external power adapter.
- You are responsible for choosing a suitable battery and following all safety precautions, to prevent
 overcharging or charging when the battery temperature is too high. The battery should be at least
 300 mAH capacity, due to the 100 mA charging current. Intel recommends battery packs with internal
 protection circuits.

Figure 4 Intel® Edison breakout board expansion board power distribution network



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2.3.1 Boot voltage selection – DCIN signal

DCIN is a signal that indicates whether Edison is being powered from a battery or from an external power source. DCIN also sets the voltage level required on VSYS in order to boot. When DCIN is floating or tied to ground, the voltage on VSYS *must* rise from 2.5 to 3.5 V in 10 ms; otherwise the boot is aborted. When the boot is aborted, power must be cycled below 2.5 V. If DCIN is connected to VSYS, Edison will start to boot when VSYS is above 2.5 V for 100 ms.

Note: When DCIN is connected to VSYS, boot will occur whenever the voltage is above 2.8 V for 100 ms. The

DCIN signal is attached to VSYS on the PCB.

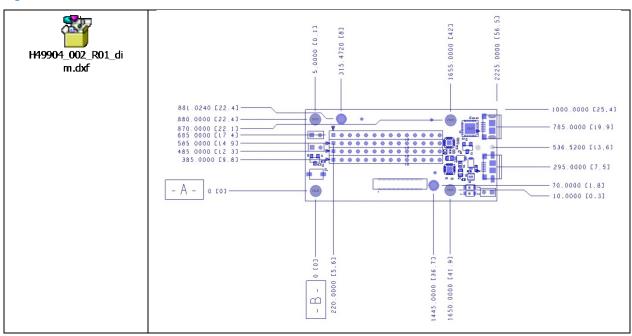
Note: The absolute minimum voltage to assure Wi-Fi and Bluetooth functionality is 3.15 V.

2.4 Intel® Edison breakout board expansion buttons

The Intel® Edison breakout board has the following buttons:

• Power button. SW1UI2 is the Intel® Edison power button. This button is configured by software. In general, pressing and holding this button down will cause the Intel® Edison module to power down. (It will leave the I/O configuration in the port expanders in its current state). Pressing this button momentarily when Edison is powered down (power still applied) will cause Intel® Edison module to reboot. If Edison is running, then a momentary press will cause Edison to go into low power sleep mode. Pressing the button momentarily when Edison is asleep, will bring Edison into full power mode.

Figure 5 Button schematic





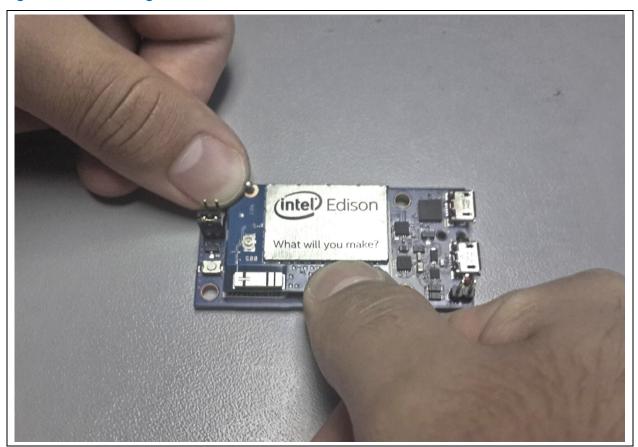
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3 Handling

When attaching an Intel® Edison module to breakout board, handle the Intel® Edison module by the PCB edges. Avoid holding or exerting pressure to the shields. To mate the Intel® Edison board to the breakout board, apply pressure directly above the connector and to the left corner.

Figure 6 Inserting an Intel® Edison module to the breakout board



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4 Debug UART Errata

The Intel® Edison board has a known error on all UARTs. When Edison goes into low power sleep, the UART internal FIFO and interface is powered down. Therefore, a two-wire UART (Rx/Tx) will lose the first received character whenever Edison is in sleep mode. In order to avoid this condition, when sleep mode is enabled, a four-wire UART (Rx, Tx, CTS, and RTS) is required.



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5 Digikey sources

Figure 7 shows some third-party accessories you can use.

Figure 7 Digikey sources



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