

Intel[®] Edison Breakout Board

Hardware Guide

January 2015

Revision 006



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Revision History

Revision	Description	Date
ww32	Initial release.	August 4, 2014
ww34	Minor edits.	August 20, 2014
001	First public release.	September 9, 2014
002	Minor corrections.	September 15, 2014
003	Added handling information.	September 30, 2014
004	Added details on the breakout board jumpers and USB connectivity. Octob	
005	Added section on software recovery mode and information on the LEDs. Novemb	
006 Minor corrections.		January 30, 2015

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1 Introduction

This document describes the Intel® Edison Breakout Board.

The Intel[®] Edison Breakout Board is designed to expose the native 1.8 V I/O of the Intel[®] Edison module. The board consists of power supply, battery recharger, USB OTG power switch, UART to USB bridge, USB OTG port, and I/O header.

1.1 References

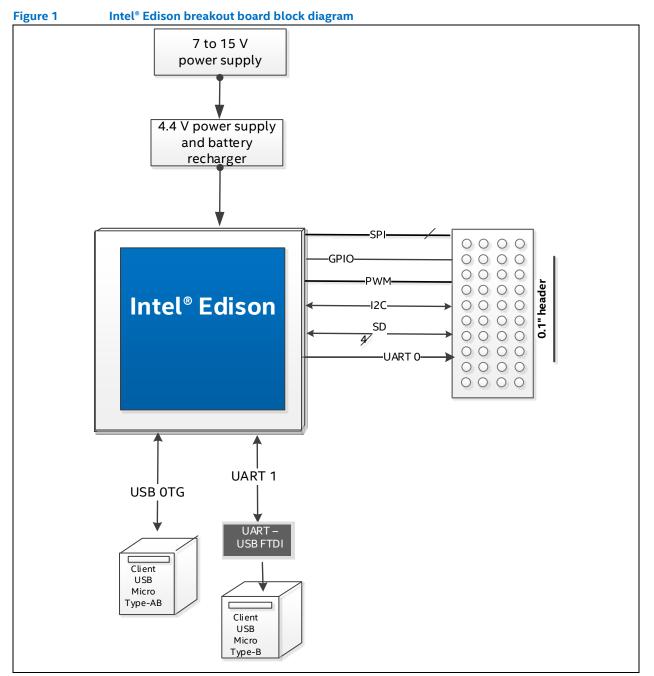
Table 1 Product-specific documents			
Reference	Name	Number/location	
331188	Intel® Edison Board Support Package User Guide		
331189	Intel [®] Edison Compute Module Hardware Guide		
331190	Intel® Edison Breakout Board Hardware Guide	(This document)	
331191	Intel® Edison Kit for Arduino* Hardware Guide		
329686	Intel [®] Galileo and Intel [®] Edison Release Notes		
[GSG]	Intel® Edison Getting Started Guide	W: http://www.intel.com/support/edison/sb/CS-035336.htm M: http://www.intel.com/support/edison/sb/CS-035344.htm L: http://www.intel.com/support/edison/sb/CS-035335.htm	
331438	Intel® Edison Wi-Fi Guide		
H49905	Intel® Edison Breakout Board Schematic	https://communities.intel.com/docs/DOC-23323	

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2 High-Level Functional Description

Figure 1 provides the block diagram for the Intel® Edison Breakout Board.





2.1 Intel[®] Edison Breakout Board jumpers

This section explains some of the jumpers on the Intel[®] Edison Breakout Board. See Figure 2 for jumper locations.

- The left pin (the square one) on J2 is +V battery; the right pin is ground.
- J2 is the battery connector. If you want to power the breakout board with a rechargeable lithium-ion battery, attach it to J2. (Refer to Figure 2 for battery polarity.) When you attach a rechargeable lithium-ion battery, the breakout board will recharge the battery whenever power is applied via J21 or J22, or via J3 (when the board is attached to a USB host).
 - **Note:** If you decide to use a battery pack on J2, we recommend a battery with a built-in thermistor. This thermistor should attach to the charger on the breakout board. If you opt for the built-in thermistor, remove the jumper on J1 and connect the thermistor to the pin labeled THERM in Figure 2. If you choose not to use a battery with built-in thermistor, leave the jumper in place.)
- J3 is a micro USB FTDI serial-to-USB converter. The Linux console will output serial stream to this USB connector.
- J16 is a fully USB compatible, micro AB, OTG (power "on the go") port. If you plug a micro A cable into this port, the Intel[®] Edison module will connect to a PC as the host; if you plug a micro B cable into this port, the Intel[®] Edison module will connect to the PC as a device. (See the USB A female to micro A male cable, Digikey P/N 10-00649 839-1105-ND in Figure 7.)
- For jumpers J17 through J20, the first pin on the left (the square one) is pin 1.
- J21 is the main power input. Apply 7 to 15 VDC with the polarity shown.
- J22 (on the bottom side of the board; see Figure 3) is for a power jack (not installed). You can purchase a 2.5 mm barrel jack (see the mini-breakout power jack in Figure 7, Digikey P/N PJ-002BH-SMT-TR CP-002BHPJCT-ND) and solder it to the bottom side of the board as shown in Figure 3. The input voltage to J22 is also 7 to 15 VDC.

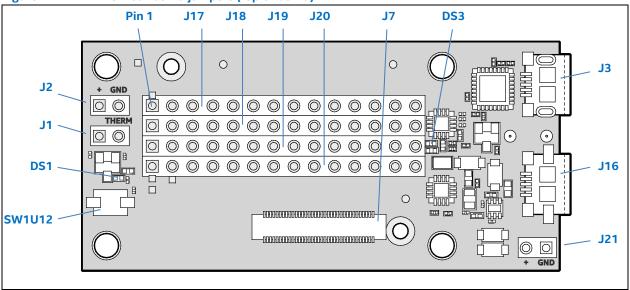
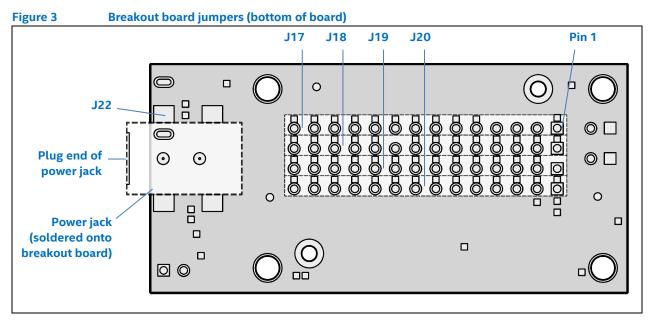


Figure 2 Breakout board jumpers (top of board)





2.1.1 USB interface

The Intel[®] Edison Breakout Board has a single USB 2.0 interface. This interface is the primary method for downloading code on J16. It is designed to support full USB "On the Go" (OTG) connections, using the ID signal. If you plug in a USB micro B connector, the breakout board will act as a USB device, and it will take its power from the USB connector.

If you plug a USB micro A connector into it, the breakout board will function as a host. When you use the Intel[®] Edison Breakout Board as a host in this manner, you must supply external power via J21 or J22. The breakout board will convert that voltage to supply 5 V to the USB connector.

Note: If you power the breakout board with a battery, it will not supply power as a USB host.



2.2 Intel[®] Edison Breakout Board expansion header

This section explains the expansion header.

When the pin mode is chosen as GPIO, it can be programmed as an output or input. When programmed as an input, a GPIO can serve as an interrupt or wake source. Inputs have programmable pullups or pulldowns. Pullup value can be 2, 20, or 50 kohm. I2C pins also have an additional 910 ohm value.

When in general purpose mode, input GPIO signals enter a glitch filter by default, before reaching the edge detection registers. To ensure that a pulse is detected by the edge detection register, the pulse should be five clock cycles long.

- 100 ns for a 50 MHz clock when SoC is in S0 state.
- 260 ns for 19.2 MHz clock when SoC is in S0i1 or S0i2 State.
- 155.5 µs for 32 kHz clock (RTC) when SoC is in S0i3 State.

Most GPIO capable pins are configured as GPIO inputs during the assertion of all resets and they remain inputs until configured otherwise.

As outputs, the GPIOs can be individually cleared or set. They can be pre-programmed to either state when entering standby. Output drive is ±3 mA.

Pin		akout board expansi	Description
J17 - pin 1	GP182_PWM2		GPIO capable of PWM output.
J17 - pin 2	NC		No connect.
J17 - pin 3	NC		No connect.
J17 - pin 4	VIN		7 to 15 V.
J17 - pin 5	GP135	UART2_TX	GPIO, UART2 transmit output.
J17 - pin 6	RCVR_MODE		Firmware recovery mode.
J17 - pin 7	GP27	I2C6_SCL	GPIO,IC26 SCL output open collector.
J17 - pin 8	GP20	I2C1_SDA	GPIO, I2C1 data open collector.
J17 - pin 9	GP28	I2C6_SDA	GPIO, I2C6 data open collector.
J17 - pin 10	GP111	SSP5_FS1	GPIO, SSP2 chip select 2 output.
J17 - pin 11	GP109	SSP5_CLK	GPIO, SSP5 clock output.
J17 - pin 12	GP115	SSP5_TXD	GPIO, SSP5 transmit data output.
J17 - pin 13	OSC_CLK_OUT_0		High speed clock output.
J17 - pin 14	GP128	UART1_CTS	GPIO, UART1 clear to send input.
J18 - pin 1	GP13_PWM1		GPIO capable of PWM output.
J18 - pin 2	GP165		GPIO
J18 - pin 3	GPI_PWRBTN_N		Power button input.
J18 - pin 4	MSIC_SLP_CLK2		32 kHz sleep clock.
J18 - pin 5	V_VBAT_BKUP		RTC backup battery input.
J18 - pin 6	GP19	I2C1_SCL	GPIO,IC21 SCL output open collector.
J18 - pin 7	GP12_PWM0		GPIO capable of PWM output.
J18 - pin 8	GP183_PWM3		GPIO capable of PWM output.
J18 - pin 9	NC		No connect.
J18 - pin 10	GP110	SSP5_FS0	GPIO, SSP1 chip select 2 output.
J18 - pin 11	GP114	SSP5_RX	GPIO, SSP5 receive data input.

Table 2 Intel[®] Edison breakout board expansion header signal list



PinImage: ConstructionJ18 - pin 12GP129UART1_RTSGP10, UART1 ready to send output.J18 - pin 13GP130UART1_RXGP10, UART1 ready to send output.J18 - pin 14FW_RCVRFirmware recovery, active high on boot.J20 - pin 14V_VSYSLACCESystem input power.J20 - pin 2V_V3P30System 3.3 V output.J20 - pin 3GP134UART2_RXUART2_RX (input).J20 - pin 4GP45COMPASS_DRDYGP10, compass data ready input.J20 - pin 5GP47ACCELEROMETER_INT_2GP10, accelerometer interrupt input 2.J20 - pin 6GP49GYRO_INTGP10, gyro interrupt input.J20 - pin 7GP15GP10, SD1 clock feedback input.J20 - pin 8GP84SD_CLK_FBGP10, SD2 clock feedback input.J20 - pin 9GP42SSP2_RXDGP10, SD2 clock output.J20 - pin 10GP41SSP2_FSGP10, SD clock headback input.J20 - pin 11GP79SD_CLKGP10, SD clock output.J20 - pin 12GP19SD_DATOGP10, SD clock output.J20 - pin 13GP80SD_DATOGP10, SD clock output.J20 - pin 14GP81SD_DATIGP10, SD clock output.J20 - pin 15GP44SD_DATIGP10, SD clock output.J20 - pin 14GP44ALS_INT_NGP10, ALS interrupt input.J19 - pin 3GNOGround.Ground.J19 - pin 4GP44ALS_INT_NGP10, ALS interrupt input.J19 - pin 6GP44G				1
J18 - pin 13GP130UART1_RXGPIO, UART1 receive data input.J18 - pin 14FW_RCVRFirmware recovery, active high on boot.J20 - pin 1V_VSYSSystem input power.J20 - pin 2V_V3P30System 3.3 V output.J20 - pin 3GP134UART2_RXUART2 Rx (input).J20 - pin 4GP45COMPASS_DRDYGPIO, compass data ready input.J20 - pin 5GP47ACCELEROMETER_INT_2GPIO, compass data ready input.J20 - pin 6GP49GYRO_INTGPIO, gyro interrupt input 2.J20 - pin 7GP15GP10GPIO.J20 - pin 8GP84SD_CLK_FBGPIO, SD clock feedback input.J20 - pin 9GP42SSP2_RXDGPIO, SD clock feedback input.J20 - pin 10GP41SSP2_FSGPIO, SD clock output.J20 - pin 11GP78SD_CLKGPIO, SD clock output.J20 - pin 12GP79SD_CMDGPIO, SD clock output.J20 - pin 13GP80SD_DATOGPIO, SD clock output.J20 - pin 14GP81SD_DAT1GP81 SD data 1.J19 - pin 1NCNo connet.J19 - pin 1NCSystem 1.8 VI/O output power.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPIO, Ascierometer interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPIO, accelerometer interrupt input.J19 - pin 6GP44ALS_INT_NGPIO, Ascierometer interrupt input.J19 - pin 7RESET_OUT#GPIO, COECE_INTGPIO,	Pin			Description
J18 - pin 14 FW_RCVR Firmware recovery, active high on boot. J20 - pin 1 V_VSYS System input power. J20 - pin 2 V_V3P30 System 3.3 V output. J20 - pin 3 GP134 UART2_RX UART2 Rx (input). J20 - pin 4 GP45 COMPASS_DRDY GPI0, compass data ready input. J20 - pin 5 GP47 ACCELEROMETER_INT_2 GPI0, accelerometer interrupt input 2. J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input. J20 - pin 7 GP15 GPI0, GPI0, SD clock feedback input. J20 - pin 8 GP48 SD_CLK_FB GPI0, SD clock feedback input. J20 - pin 10 GP41 SSP2_FS GPI0, SD clock output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD clock output. J20 - pin 13 GP80 SD_DAT1 GPB1 SD data 1. J19 - pin 1 NC No connect. J19 - pin 3 J19 - pin 3 GND Ground. Ground. J19 - pin 4	J18 - pin 12	GP129	UART1_RTS	GPIO, UART1 ready to send output.
J20 - pin 1V_VSYSIndext System input power.J20 - pin 2V_J3P30System 3.3 V output.J20 - pin 3GP134UART2_RXUART2 Rx (input).J20 - pin 4GP45COMPASS_DRDYGPI0, compass data ready input.J20 - pin 5GP47ACCELEROMETER_INT_2GPI0, accelerometer interrupt input 2.J20 - pin 6GP49SYRO_NITGPI0, gyro interrupt input.J20 - pin 7GP15GPI0.J20 - pin 8GP44SD_CLK_FBGPI0, SD clock feedback input.J20 - pin 9GP42SSP2_RXDGPI0, SSP2 Rx data input.J20 - pin 10GP41SSP2_FSGPI0, SD clock output.J20 - pin 11GP78SD_CLKGPI0, SD clock output.J20 - pin 12GP79SD_MDGPI0, SD clock output.J20 - pin 13GP80SD_DAT0GPI0, SD clock output.J20 - pin 14GP81SD_DAT1GP81 SD data 0.J20 - pin 15NCNo connect.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPI0, ALS interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPI0, accelerometer interrupt input.J19 - pin 6GP48GYRO_DRDYGPI0, accelerometer interrupt input.J19 - pin 7RESET_OUT#GPI0, ALS interrupt input.J19 - pin 8GP14ALS_INT_NGPI0, accelerometer interrupt input.J19 - pin 10GP40SSP2_TXDGPI0, ALS interrupt input.J19 - pin 7RESET_OUT#GPI0, ALS Interrupt input. </td <td>J18 - pin 13</td> <td>GP130</td> <td>UART1_RX</td> <td>GPIO, UART1 receive data input.</td>	J18 - pin 13	GP130	UART1_RX	GPIO, UART1 receive data input.
J20 - pin 2 V_V3P30 System 3.3 V output. J20 - pin 3 GP134 UART2_RX UART2 Rx (input). J20 - pin 4 GP45 COMPASS_DRDY GPI0, compass data ready input. J20 - pin 5 GP47 ACCELEROMETER_INT_2 GPI0, accelerometer interrupt input 2. J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input. J20 - pin 7 GP15 GPI0. GPI0. J20 - pin 8 GP42 SSp2_RXD GPI0, SSP2 Rx data input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 frame sync output. J20 - pin 10 GP41 SSP2_FS GPI0, SD clock output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD clock output. J20 - pin 13 GP80 SD_DAT0 GPI0, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 3 GND Ground. Ground. J19 - pin 4 GP44 ALS_INT_M GPI0, ALS interrupt input. J19	J18 - pin 14	FW_RCVR		Firmware recovery, active high on boot.
J20 - pin 3GP134UART2_RXUART2 Rx (input).J20 - pin 4GP45COMPASS_DRDYGPI0, compass data ready input.J20 - pin 5GP47ACCELEROMETER_INT_2GPI0, accelerometer interrupt input 2.J20 - pin 6GP49GYRO_INTGPI0, gyro interrupt input.J20 - pin 7GP15FMGPI0, SD clock feedback input.J20 - pin 8GP42SSP2_RXDGPI0, SD clock feedback input.J20 - pin 9GP42SSP2_RXDGPI0, SD clock feedback input.J20 - pin 10GP41SSP2_FSGPI0, SD clock output.J20 - pin 11GP78SD_CLKGPI0, SD clock output.J20 - pin 12GP79SD_CMDGPI0, SD clock output.J20 - pin 13GP80SD_LATOGPI0, SD clock output.J20 - pin 14GP81SD_DAT1GP81 SD data 0.J20 - pin 15GP44SD_DAT1GP81 SD data 1.J19 - pin 1NCNc connect.J19 - pin 2V_V1P80Ground.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPI0, ALS interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPI0, accelerometer interrupt input.J19 - pin 6GP43GYR_DRDYGPI0, uadia code uiterrupt input.J19 - pin 7RESET_OUT#MAT1_TXGPI0, UART 1 Tx output.J19 - pin 8GP13UART1_TXGPI0, UART 1 Tx output.J19 - pin 9GP14AUDIO_CODEC_INTGPI0, SSP2 clock output.J19 - pin 10GP40SSP2_CLK	J20 - pin 1	V_VSYS		System input power.
J20 - pin 4 GP45 COMPASS_DRDY GPI0, compass data ready input. J20 - pin 5 GP47 ACCELEROMETER_INT_2 GPI0, accelerometer interrupt input 2. J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input. J20 - pin 7 GP15 GPI0. GPI0. J20 - pin 8 GP84 SD_CLK_FB GPI0, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPI0, SD clock output. J20 - pin 11 GP78 SD_CMD GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD data 0. J20 - pin 13 GP80 SD_DAT0 GPI0, SD data 1. J19 - pin 1 NC No connect. J19 - pin 3 J19 - pin 3 GND Ground. J19 - pin 3 J19 - pin 4 GP44 ALS_INT_N GPI0, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPI0, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPI0, accel	J20 - pin 2	V_V3P30		System 3.3 V output.
J20 - pin 5 GP47 ACCELEROMETER_INT_2 GPI0, accelerometer interrupt input 2. J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input. J20 - pin 7 GP15 GPI0. J20 - pin 8 GP84 SD_CLK_FB GPI0., SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPI0, SD clock output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD clock output. J20 - pin 13 GP80 SD_DATO GPI0, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 3 J19 - pin 3 GND Ground. J19 - pin 4 J19 - pin 4 GP44 ALS_INT_N GPI0, accelerometer interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPI0, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPI0, accelerometer interrupt input.<	J20 - pin 3	GP134	UART2_RX	UART2 Rx (input).
J20 - pin 6 GP49 GYRO_INT GPI0, gyro interrupt input. J20 - pin 7 GP15 GP15 GP10. J20 - pin 8 GP84 SD_CLK_FB GP10, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GP10, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GP10, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GP10, SD clock output. J20 - pin 12 GP79 SD_CMD GP10, SD clock output. J20 - pin 13 GP80 SD_DATO GP10, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J11 J19 - pin 3 GND Ground. Ground. J19 - pin 4 GP44 ALS_INT_N GP10, accelerometer interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GP10, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GP10, audio codec interrupt input. J19 - pin 7 RESET_OUT# GP10, audio codec interrupt input. GP13	J20 - pin 4	GP45	COMPASS_DRDY	GPIO, compass data ready input.
J20 - pin 7 GP15 GP10 J20 - pin 8 GP84 SD_CLK_FB GPI0, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPI0, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPI0, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPI0, SD clock output. J20 - pin 12 GP79 SD_CMD GPI0, SD clock output. J20 - pin 13 GP80 SD_DATO GPI0, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 3 J19 - pin 3 GND Ground. Ground. J19 - pin 4 GP44 ALS_INT_N GPI0, SD data ready input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPI0, ALS interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPI0, gyro data ready input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 J19 - pin 8 GP131 UART1_TX GPI0, gyro data ready input. J19 - pi	J20 - pin 5	GP47	ACCELEROMETER_INT_2	GPIO, accelerometer interrupt input 2.
J20 - pin 8 GP84 SD_CLK_FB GPIO, SD clock feedback input. J20 - pin 9 GP42 SSP2_RXD GPIO, SSP2 Rx data input. J20 - pin 10 GP41 SSP2_FS GPIO, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPIO, SD clock output. J20 - pin 12 GP79 SD_CMD GPIO, SD clock output. J20 - pin 13 GP80 SD_DATO GPIO, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC Rest No connect. J19 - pin 2 V_V1P80 Soccence. System 1.8 V I/O output power. J19 - pin 3 GND GROUND. Ground. J19 - pin 4 GP44 ALS_INT_N GPIO, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPIO, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPIO, uptot power. J19 - pin 7 RESET_OUT# GPIO, UART 1 Tx output. J19 - pin 8 GP131 UART1_TX GPIO, SSP2 clock output.	J20 - pin 6	GP49	GYRO_INT	GPIO, gyro interrupt input.
J20 - pin 9GP42SSP2_RXDGPIO, SSP2 Rx data input.J20 - pin 10GP41SSP2_FSGPIO, SSP2 frame sync output.J20 - pin 11GP78SD_CLKGPIO, SD clock output.J20 - pin 12GP79SD_CMDGPIO, SD command.J20 - pin 13GP80SD_DATOGPIO, SD data 0.J20 - pin 14GP81SD_DAT1GP81 SD data 1.J19 - pin 1NCNo connect.J19 - pin 2V_V1P80Ground.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPIO, ALS interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPIO, accelerometer interrupt input.J19 - pin 6GP48GYRO_DRDYGPIO, uptor to uptor.J19 - pin 7RESET_OUT#AUDIO_CODEC_INTGPIO, accelerometer interrupt input.J19 - pin 8GP131UART1_TXGPIO, uptor data ready input.J19 - pin 10GP40SSP2_CLKGPIO, SSP2 clock output.J19 - pin 11GP43SSP2_TXDGPIO, SSP2 clock output.J19 - pin 12GP77SD_CDNGPIO, SD card detect low input.J19 - pin 13GP82SD_DAT2GPIO, SD data 2	J20 - pin 7	GP15		GPIO.
J20 - pin 10 GP41 SSP2_FS GPIO, SSP2 frame sync output. J20 - pin 11 GP78 SD_CLK GPIO, SD clock output. J20 - pin 12 GP79 SD_CMD GPIO, SD clock output. J20 - pin 12 GP79 SD_DATO GPIO, SD data 0. J20 - pin 13 GP80 SD_DATO GP81 SD data 1. J19 - pin 1 NC Image: No connect. No connect. J19 - pin 2 V_V1P80 System 1.8 V I/O output power. J19 - pin 3 GND Ground. Ground. J19 - pin 4 GP44 ALS_INT_N GPIO, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPIO, gyro data ready input. J19 - pin 6 GP48 GYRO_DRDY GPIO, UART 1 Tx output. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPIO, UART 1 Tx output. J19 - pin 10 GP40 SSP2_CLK GPIO, SSP2 clock output. J19 - pin 11 GP43 SSP2_TXD GPIO, SD card detect low input. J19 - pi	J20 - pin 8	GP84	SD_CLK_FB	GPIO, SD clock feedback input.
J20 - pin 11GP78SD_CLKGPI0, SD clock output.J20 - pin 12GP79SD_CMDGPI0, SD command.J20 - pin 13GP80SD_DAT0GPI0, SD data 0.J20 - pin 14GP81SD_DAT1GP81 SD data 1.J19 - pin 1NCNo connect.J19 - pin 2V_V1P80System 1.8 V I/O output power.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPI0, ALS interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPI0, accelerometer interrupt input.J19 - pin 6GP48GYR0_DRDYGPI0, upt output.J19 - pin 7RESET_OUT#System reset out low.J19 - pin 8GP131UART1_TXGPI0, SDP2 clock output.J19 - pin 10GP40SSP2_CLKGPI0, SSP2 clock output.J19 - pin 11GP43SSP2_TXDGPI0, SDP2 clock output.J19 - pin 12GP77SD_CDNGPI0, SD card detect low input.J19 - pin 13GP82SD_DAT2GPI0, SD data 2	J20 - pin 9	GP42	SSP2_RXD	GPIO, SSP2 Rx data input.
J20 - pin 12 GP79 SD_CMD GPIO, SD command. J20 - pin 13 GP80 SD_DATO GPIO, SD data 0. J20 - pin 14 GP81 SD_DAT1 GP81 SD data 1. J19 - pin 1 NC No connect. J19 - pin 2 V_V1P80 System 1.8 V I/O output power. J19 - pin 3 GND Ground. J19 - pin 4 GP44 ALS_INT_N GPIO, ALS interrupt input. J19 - pin 5 GP46 ACCELEROMETER_INT_1 GPIO, accelerometer interrupt input. J19 - pin 6 GP48 GYRO_DRDY GPIO, gyro data ready input. J19 - pin 7 RESET_OUT# System reset out low. J19 - pin 8 GP131 UART1_TX GPIO, audio codec interrupt input. J19 - pin 9 GP14 AUDIO_CODEC_INT GPIO, SSP2 clock output. J19 - pin 10 GP43 SSP2_TXD GPIO, SSP2 transmit data output. J19 - pin 12 GP77 SD_CDN GPIO, SD card detect low input. J19 - pin 13 GP82 SD_DAT2 GPIO, SD data 2	J20 - pin 10	GP41	SSP2_FS	GPIO, SSP2 frame sync output.
J20 - pin 13GP80SD_DAT0GPIO, SD data 0.J20 - pin 14GP81SD_DAT1GP81 SD data 1.J19 - pin 1NCNo connect.J19 - pin 2V_V1P80System 1.8 V I/O output power.J19 - pin 3GNDGround.J19 - pin 4GP44ALS_INT_NGPIO, ALS interrupt input.J19 - pin 5GP46ACCELEROMETER_INT_1GPIO, accelerometer interrupt input.J19 - pin 6GP48GP48GYRO_DRDYJ19 - pin 7RESET_OUT#J19 - pin 8GP131J19 - pin 9GP14AUDIO_CODEC_INTGPIO, audio codec interrupt input.J19 - pin 10GP40SSP2_TXDGPIO, SSP2 clock output.J19 - pin 12GP77SD_CDNGPIO, SD card detect low input.J19 - pin 13GP82SD_DAT2GPIO, SD data 2	J20 - pin 11	GP78	SD_CLK	GPIO, SD clock output.
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J19 - pin 6GP48GYRO_DRDYGPIO, gyro data ready input.J19 - pin 7RESET_OUT#System reset out low.J19 - pin 8GP131UART1_TXGPIO, UART 1 Tx output.J19 - pin 9GP14AUDIO_CODEC_INTGPIO, audio codec interrupt input.J19 - pin 10GP40SSP2_CLKGPIO, SSP2 clock output.J19 - pin 11GP43SSP2_TXDGPIO, SSP2 transmit data output.J19 - pin 12GP77SD_CDNGPIO, SD card detect low input.J19 - pin 13GP82SD_DAT2GPIO, SD data 2	J19 - pin 4	GP44	ALS_INT_N	GPIO, ALS interrupt input.
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J19 - pin 13 GP82 SD_DAT2 GPIO, SD data 2	J19 - pin 11	GP43	SSP2_TXD	GPIO, SSP2 transmit data output.
	J19 - pin 12	GP77	SD_CDN	GPIO, SD card detect low input.
J19 - pin 14 GP83 SD_DAT3 GPIO, SD data 3	J19 - pin 13	GP82	SD_DAT2	GPIO, SD data 2
	J19 - pin 14	GP83	SD_DAT3	GPIO, SD data 3

2.3 Intel[®] Edison Breakout Board expansion power supply

Intel[®] Edison is a low-power device. In general, it does not draw more than 200 mA with 600 mA short duration spikes during Wi-Fi transmit. Therefore, an Intel[®] Edison device may run on USB power (when configured as a device), or an external power adapter from 7 to 15 V.

Power from the external power adapter goes to a DC-DC converter and down-converted to 5 V. The 5 V rail is diode ORed with the USB VBUS rail. This power goes to a battery recharger IC, which limits the output voltage to 4.4 V. This voltage is in the safe range for the Edison module VSYS. The VSYS power range is 3.15 to 4.5 V. This allows the Intel® Edison device to run off a standard lithium-ion battery. The charger IC is configured to limit the current to 1 A. The charger is programmed to charge at 190 mA. This charger is designed to charge standard lithium-ion batteries with 4.2 V maximum charging voltage. You are responsible for choosing a suitable battery and following all safety precautions, to prevent overcharging or charging when the battery temperature is too high.



The drawback to this design is that the linear supply power drop places a limit on the total power through the Intel[®] Edison board and the 3.3 and 1.8 V supplies. The power loss through the charger will be (4.4 to 5 V) \cdot current. In this case, you should attempt to limit average current through the Intel[®] Edison board and its power rails to approximately 0.75 A.

The recharger IC on the Intel[®] Edison breakout board has input current limit and overtemperature shutdown. Assure the end design does not trip these protection mechanisms.

Some considerations of the power distribution in the Intel® Edison breakout board:

- 1. USB host mode always requires use of an external power adapter.
- 2. You are responsible for choosing a suitable battery and following all safety precautions, to prevent overcharging or charging when the battery temperature is too high. The battery should be at least 300 mAH capacity, due to the 100 mA charging current. Intel recommends battery packs with internal protection circuits.

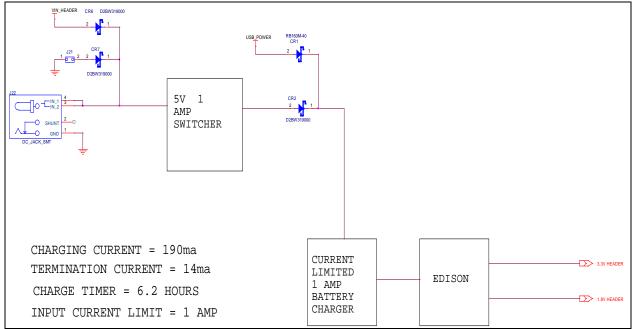


Figure 4 Intel[®] Edison breakout board expansion board power distribution network

2.3.1 Boot voltage selection – DCIN signal

DCIN is a signal that indicates whether Edison is being powered from a battery or from an external power source. DCIN also sets the voltage level required on VSYS in order to boot. When DCIN is floating or tied to ground, the voltage on VSYS *must* rise from 2.5 to 3.5 V in 10 ms; otherwise the boot is aborted. When the boot is aborted, power must be cycled below 2.5 V. If DCIN is connected to VSYS, Edison will start to boot when VSYS is above 2.5 V for 100 ms.

- *Note:* When DCIN is connected to VSYS, boot will occur whenever the voltage is above 2.8 V for 100 ms. The DCIN signal is attached to VSYS on the PCB.
- *Note:* The absolute minimum voltage to assure Wi-Fi and Bluetooth functionality is 3.15 V.



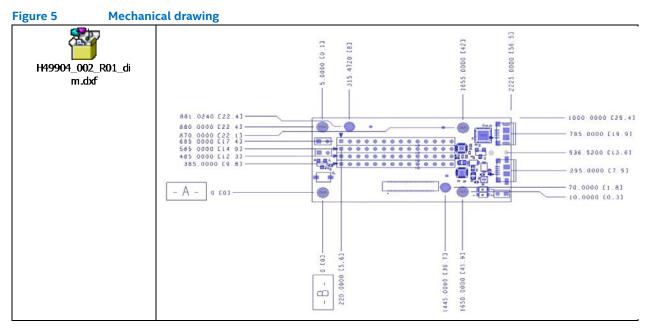
2.4 Intel[®] Edison Breakout Board buttons

The Intel® Edison breakout board (see Figure 2) has the following buttons:

- **Power button.** The power button (SW1) is configured by software. Pressing and holding the power button will produce different results depending on the current state of the Intel[®] Edison compute module and the duration of the hold:
 - When the Intel[®] Edison device is completely powered down, pressing and holding the power button for 3 seconds will power up the device and boot up the Intel[®] Edison compute module.
 - When the Intel[®] Edison device is running, pressing and holding the power button for more than
 2 seconds but less than 7 seconds will put the Intel[®] Edison device into AP (access point) mode. This action enables the "one-time setup" (same as *configure_edison --enableOneTimeSetup*).
 - When the Intel[®] Edison device is running, pressing and holding the power button for 10 seconds or more will cause the Intel[®] Edison compute module to power down. This is similar to a hard shutdown, which cuts the power supply to the compute module.

2.5 Intel[®] Edison Breakout Board mechanical drawing

Figure 5 shows a mechanical drawing of the Intel® Edison Breakout Board, in DXF format.



2.6 LEDs

The Intel[®] Edison Breakout Board has two LEDs. There is no direct control over these LEDs, so they are described here for informational purposes.

- DS1 is the reset LED. (See Figure 2 for location.) It will turn on when the Intel[®] Edison processor is running. When the processor is in reset and asserting RESET_OUT# low, it will turn off.
- DS3 is the charging LED. (See Figure 2 for location.) It will turn on when the BQ24074 is charging an attached battery.

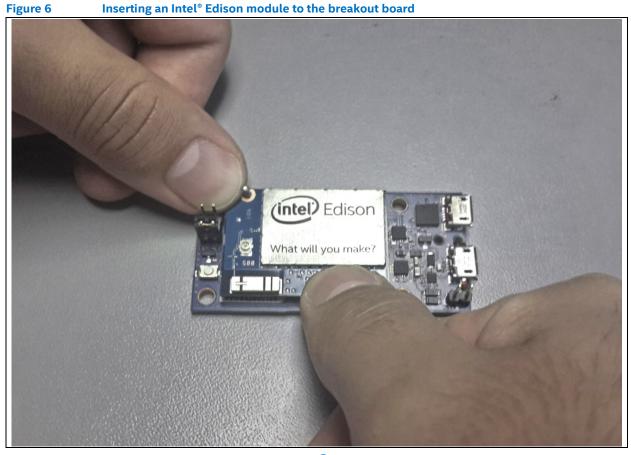
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3 Handling

When attaching an Intel[®] Edison module to breakout board, handle the Intel[®] Edison module by the PCB edges. Avoid holding or exerting pressure to the shields. To mate the Intel[®] Edison board to the breakout board, apply pressure directly above the connector and to the left corner.



§



4 Digikey sources

Figure 7 shows some third-party accessories you can use.

